## JAYPEE UNIVERSITY OF INFORMATION TECHNOLOGY, WAKNAGHAT TEST -2 EXAMINATION- 2024

MTech - II Semester (CM)

COURSE CODE(CREDITS): 10M11CE212 (3)

MAX. MARKS: 25

COURSE NAME: Heavy Civil Construction Equipment, Methods, and Management

COURSE INSTRUCTORS: Saurabh Rawat

MAX. TIME: 1 Hour 30 Minutes

Note: (a) All questions are compulsory.

(b) Marks are indicated against each question in square brackets.

- (c) The candidate is allowed to make Suitable numeric assumptions wherever required for solving problems
- Q1) Calculate the hourly ownership cost for the second year of operation of a 465 hp twin-engine scraper. This equipment will be operated 8 h/day and 250 days/year in average conditions. Use the sum-of-years-digits method of depreciation for the following information:

Parameter	Value
Initial cost	₹ 18600
Tire Cost	₹ 14000
Estimated Life	5 years
Salvage value	₹ 22000
Interest on the investment	8%
Insurance	1.5%
Taxes	3%
Storage	0.5%
Fuel price	₹2.00/gal
Operator's wages	₹ 24.60/hour

CO3[5]

- Q2) Elaborating the principles of 'Caterpillar Method', explain how the method is used for calculating the 'ownership cost' of a 150-t truck crane.

  CO3[5]
- Q3) With the help of a diagram, explain the construction of an under reamed pile. CO4 [3]
- Q4) A 140H motor grader with a 3.66 m (12 ft) moldboard is performing road maintenance on a township road. The machine is working at an average speed of 13 km/h (8 mph) with a moldboard carry angle of 60°. What is the motor grader's production (m²/hr) based on coverage area? Take: Job efficiency of 0.90 and effective blade length is 3.17 m (10.4 ft).

CO3[5]

- Q5) The fixed cost for the year 2023-2024 is ₹ 60,000. The estimated sales for the period is ₹ 2 lakhs. The variable cost per unit for the single product made is ₹ 5. If each unit sells at ₹ 25 and number of unit input value coincides with the expected value of output, then determine:
  - a) Breakeven point
  - b) The profit earned at the turnover of ₹ 1,25,000
  - e) Margin of safety

CO3, CO4[3+2+2=7]