

Mohit-Gang.

JAYPEE UNIVERSITY OF INFORMATION TECHNOLOGY, WAKNAGHAT

TEST -2 EXAMINATION- December 2017

B. Tech VIIth Semester

COURSE CODE: 17B1WEC733

MAX. MARKS: 25

COURSE NAME: ROBOTIC SYSTEMS AND CONTROL

COURSE CREDITS: 3

MAX. TIME: 1.5 hrs

Note: All questions are compulsory. Carrying of mobile phone during examinations will be treated as case of unfair means. Make valid assumptions if required.

1. [7 marks] Derive the mathematical model of the PMDC motor. Draw a block diagram of linear control of robot manipulator and explain it.
2. [8 marks] Design a PID compensator for the regulation problem of robot manipulator. Perform the steady-state error analysis using PID control scheme. Explain all the advantages of PID over PD compensator.
3. [4 marks] What are the control issues in robotic control? Explain point-to-point motion and trajectory tracking problem.
4. [1.5 marks each] Write short notes on:
 - a. Servomechanism
 - b. Gear reduction
 - c. Zeigler-Nichols tuning method
 - d. Euler-Lagrange approach

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