

Unmanned Aerial Vehicles for Internet of Things (IoT)

Concepts, Techniques, and Applications

Edited by
Vandana Mohindru,
Yashwant Singh,
Ravindara Bhatt
and
Anuj Kumar Gupta



WILEY

This edition first published 2021 by John Wiley & Sons, Inc., 111 River Street, Hoboken, NJ 07030, USA and Scrivener Publishing LLC, 100 Cummings Center, Suite 541J, Beverly, MA 01915, USA © 2021 Scrivener Publishing LLC

For more information about Scrivener publications please visit www.scrivenerpublishing.com.

All rights reserved. No part of this publication may be reproduced, stored in a retrieval system, or transmitted, in any form or by any means, electronic, mechanical, photocopying, recording, or otherwise, except as permitted by law. Advice on how to obtain permission to reuse material from this title is available at http://www.wiley.com/go/permissions.

Wiley Global Headquarters

111 River Street, Hoboken, NJ 07030, USA

For details of our global editorial offices, customer services, and more information about Wiley products visit us at www.wiley.com.

Limit of Liability/Disclaimer of Warranty

While the publisher and authors have used their best efforts in preparing this work, they make no representations or warranties with respect to the accuracy or completeness of the contents of this work and specifically disclaim all warranties, including without limitation any implied warranties of merchantability or fitness for a particular purpose. No warranty may be created or extended by sales representatives, written sales materials, or promotional statements for this work. The fact that an organization, website, or product is referred to in this work as a citation and/or potential source of further information does not mean that the publisher and authors endorse the information or services the organization, website, or product may provide or recommendations it may make. This work is sold with the understanding that the publisher is not engaged in rendering professional services. The advice and strategies contained herein may not be suitable for your situation. You should consult with a specialist where appropriate. Neither the publisher nor authors shall be liable for any loss of profit or any other commercial damages, including but not limited to special, incidental, consequential, or other damages. Further, readers should be aware that websites listed in this work may have changed or disappeared between when this work was written and when it is read.

Library of Congress Cataloging-in-Publication Data

ISBN 978-1-119-76882-1

Cover image: Pixabay.Com

Cover design by Russell Richardson

Set in size of 11pt and Minion Pro by Manila Typesetting Company, Makati, Philippines

Printed in the USA

10 9 8 7 6 5 4 3 2 1

Contents

Pı	efac	<u>e</u>			XV	
L	Uni	Inmanned Aerial Vehicle (UAV): A Comprehensive Survey				
	Rohit Chaurasia and Vandana Mohindru					
	1.1	Intro	duction			
	1.2	Relate	ed Work			
	1.3	UAV	Technolo	gy		
		1.3.1	UAV Pla	atforms		
			1.3.1.1	Fixed-Wing Drones		
				Multi-Rotor Drones		
			1.3.1.3	Single-Rotor Drones		
				Fixed-Wing Hybrid VTOL		
		1.3.2		ies of the Military Drones		
				ones Work		
			1.3.3.1	Firmware—Platform Construction		
				and Design		
		1.3.4	Compai	rison of Various Technologies	1	
			1.3.4.1	Drone Types & Sizes	1	
			1.3.4.2	Radar Positioning and Return to Home	J	
			1.3.4.3	GNSS on Ground Control Station	1	
			1.3.4.4	Collision Avoidance Technology		
				and Obstacle Detection]	
			1.3.4.5	Gyroscopic Stabilization, Flight		
				Controllers and IMU]	
			1.3.4.6	UAV Drone Propulsion System	J	
			1.3.4.7	Flight Parameters Through Telemetry]	
			1.3.4.8	Drone Security & Hacking	1	
			1.3.4.9	3D Maps and Models With Drone Sensors	J	
		1.3.5	UAV Co	ommunication Network	1	
			1.3.5.1	Classification on the Basis of Spectrum		
				Perspective]	

vi Contents

			1.3.5.2	Various Types of Radiocommunication
				Links
			1.3.5.3	VLOS (Visual Line-of-Sight) and BLOS
				(Beyond Line-of-Sight) Communication
				in Unmanned Aircraft System
			1.3.5.4	Frequency Bands for the Operation of UAS
			1.3.5.5	Cellular Technology for UAS Operation
	1.4	Appli	cation of	UAV
		1.4.1	In Milit	ary
		1.4.2	In Geon	morphological Mapping and Other
			Similar	Sectors
		1.4.3	In Agric	culture
	1.5	UAV	Challenge	es
	1.6	Conc	lusion an	d Future Scope
		Refer	ences	
2	Unr	nanne	d Aerial V	Vehicles: State-of-the-Art, Challenges
_			e Scope	The late of the la
				uradha Basu
			duction	
	2.2		nical Chal	llenges
				ons in Channel Characteristics
		2.2.2		ssisted Cellular Network Planning
				visioning
		2.2.3		eter Wave Cellular Connected UAVs
		2.2.4		ment of UAV
		2.2.5		ory Optimization
		2.2.6		ard Energy
	2.3	Conc		
			ences	
3	Date	+ 0 m m m	d Enonce	Managament in HAV Based Nativoulis
<u> </u>				Management in UAV-Based Networks ool Vasudeva and Manu Sood
			duction	ioi vasaaeva ana mana 300a
	3.1			Energy Management in LIAM Recod
	3.2			Energy Management in UAV-Based on Networks
		3.2.1	Unpred: UAV Ne	ictable Trajectories of UAVs in Cellular
		2 2 2		
		$\frac{3.2.2}{2.2.2}$		omogeneous Power Consumption
		3.2.3		andwidth Requirement/Low Spectrum
			Availabi	ility/Spectrum Scarcity

		Contents	vii
	3.2.4	Short-Range Line-of-Sight Communication	48
	3.2.5	Time Constraint (Time-Limited Spectrum Access)	48
	3.2.6	*	49
	3.2.7	The Joint Design for the Sensor Nodes' Wake-Up	
		Schedule and the UAV's Trajectory (Data Collection)	49
3.3	Efficie	ent Battery and Energy Management Proposed	
	Techn	iques in Literature	50
	3.3.1	Cognitive Radio (CR)-Based UAV Communication	
		to Solve Spectrum Congestion	<u>51</u>
	3.3.2	Compressed Sensing	<u>52</u>
	3.3.3	Power Allocation and Position Optimization	53
	3.3.4	Non-Orthogonal Multiple Access (NOMA)	<u>53</u>
	3.3.5	Wireless Charging/Power Transfer (WPT)	<u>54</u>
	3.3.6	UAV Trajectory Design Using a Reinforcement	
		Learning Framework in a Decentralized Manner	<u>55</u>
	3.3.7	Efficient Deployment and Movement of UAVs	55
	3.3.8	3D Position Optimization Mixed With Resource	
		Allocation to Overcome Spectrum Scarcity	
		and Limited Energy Constraint	<u>56</u>
	3.3.9	UAV-Enabled WSN: Energy-Efficient Data	
		Collection	<u>57</u>
		Trust Management	<u>57</u>
		Self-Organization-Based Clustering	<u>58</u>
		Bandwidth/Spectrum-Sharing Between UAVs	59
		Using Millimeter Wave With SWIPT	59
		Energy Harvesting	<u>60</u>
3.4	Concl		<u>61</u>
	Refere	ences	<u>67</u>
Ene	rgy Effi	cient Communication Methods for Unmanned	
		cles (UAVs): Last Five Years' Study	73
	esh Kui	•	
4.1		luction	73
		Introduction to UAV	74
		Communication in UAV	75
4.2		ture Survey Process	77
	4.2.1	Research Questions	77
		Information Source	77
4.3		ng in UAV	78
	4.3.1	Communication Methods in UAV	78
		4.3.1.1 Single-Hop Communication	79

viii Contents

		4.3.1.2 Multi-Hop Communication	80
	4.4	Challenges and Issues	82
		4.4.1 Energy Consumption	82
		4.4.2 Mobility of Devices	82
		4.4.3 Density of UAVs	82
		4.4.4 Changes in Topology	85
		4.4.5 Propagation Models	85
		4.4.6 Security in Routing	85
	4.5	Conclusion	<u>85</u>
		References	86
5	A R	eview on Challenges and Threats to Unmanned	
		ial Vehicles (UAVs)	89
		ik Johny Basha and Jagan Mohan Reddy Danda	
	5.1		89
		Applications of UAVs and Their Market Opportunity	90
		5.2.1 Applications	90
		5.2.2 Market Opportunity	92
	5.3	Attacks and Solutions to Unmanned Aerial Vehicles (UAVs)	92
		5.3.1 Confidentiality Attacks	93
		5.3.2 Integrity Attacks	95
		5.3.3 Availability Attacks	96
		5.3.4 Authenticity Attacks	97
	5.4	Research Challenges	99
		5.4.1 Security Concerns	99
		5.4.2 Safety Concerns	99
		5.4.3 Privacy Concerns	100
		5.4.4 Scalability Issues	100
		5.4.5 Limited Resources	100
	5.5	Conclusion	101
		References	101
6	Inte	rnet of Things and UAV: An Interoperability Perspective	105
		rti Rana and Yashwant Singh	
	6.1	Introduction	106
	6.2	Background	108
		6.2.1 Issues, Controversies, and Problems	109
	6.3	Internet of Things (IoT) and UAV	110
	6.4	Applications of UAV-Enabled IoT	113
	6.5	Research Issues in UAV-Enabled IoT	114
	6.6	High-Level UAV-Based IoT Architecture	117

			CONTENTS	1X
		6.6.1 UAV Overview		117
		6.6.2 Enabling IoT Scalability		119
		6.6.3 Enabling IoT Intelligence		120
		6.6.4 Enabling Diverse IoT Applications		121
	6.7			121
	6.8			123
		References		124
7	Pra	ctices of Unmanned Aerial Vehicle (UAV)		
	for S	Security Intelligence		<u>129</u>
	Swa	rnjeet Kaur, Kulwant Singh and Amanpreet Singh		
	7.1	Introduction		130
	7.2	Military		132
	7.3	Attack		<u>133</u>
	7.4	Journalism		134
	7.5	Search and Rescue		136
	7.6	Disaster Relief		<u>138</u>
	7.7	Conclusion		139
		References		139
3	Blo	ckchain-Based Solutions for Various Security		
	Issu	es in UAV-Enabled IoT		143
	Mac	dhuri S. Wakode and Rajesh B. Ingle		
	8.1	Introduction		<u>144</u>
		8.1.1 Organization of the Work		145
	8.2	Introduction to UAV and IoT		145
		8.2.1 UAV		145
		8.2.2 IoT		146
		8.2.3 UAV-Enabled IoT		147
		8.2.4 Blockchain		<u>150</u>
	8.3	,		<u>151</u>
	8.4	1	sues	153
		Research Directions		154
		Conclusion		154
	8.7			155
		References		155
•		cient Energy Management Systems in UAV-Based		
		Networks		<u>159</u>
		Iounika Reddy, Neelima K. and G. Naresh		
	9.1	Introduction		160
	9.2	Energy Harvesting Methods		161

x Contents

		9.2.1	Basic Energy Harvesting Mechanisms	162			
		9.2.2	Markov Decision Process-Based Energy				
			Harvesting Mechanisms	163			
		9.2.3	mm Wave Energy Harvesting Mechanism	164			
		9.2.4	Full Duplex Wireless Energy Harvesting				
			Mechanism	165			
	9.3	Energy	y Recharge Methods	165			
	9.4	Efficie	nt Energy Utilization Methods	166			
		9.4.1	GLRM Method	<u>166</u>			
		9.4.2	DRL Mechanism	167			
		9.4.3	Onboard Double Q-Learning Mechanism	168			
		9.4.4	Collision-Free Scheduling Mechanism	168			
	9.5	Concl	<u>usion</u>	<u>170</u>			
		Refere	nces	170			
10	A Su	irvev oi	n IoE-Enabled Unmanned Aerial Vehicles	173			
			thraju, R. Dhivyadevi, M. Supriya,	1,0			
	B. Jaishankar and Shanmugaraja T.						
		1 Introduction					
	10.2	Over	view of Internet of Everything	176			
		10.2.		176			
		10.2.2		177			
			10.2.2.1 Scalability	177			
			10.2.2.2 Intelligence	178			
			10.2.2.3 Diversity	178			
		10.2.3		179			
			10.2.3.1 Enabling Scalability	179			
			10.2.3.2 Enabling Intelligence	180			
			10.2.3.3 Enabling Diversity	180			
		10.2.4	4 Challenges of IoE	181			
			10.2.4.1 Coverage Constraint	181			
			10.2.4.2 Battery Constraint	181			
			10.2.4.3 Computing Constraint	181			
			10.2.4.4 Security Constraint	182			
	10.3	Over	view of Unmanned Aerial Vehicle (UAV)	182			
		10.3.		183			
		10.3.2	2 UAV Communication Networks	183			
			10.3.2.1 Ad Hoc Multi-UAV Networks	183			
			10.3.2.2 UAV-Aided Communication Networks	184			

11.7 Future Work

References

203

203

xii Contents

2	UAV with Amphibious Landing, Processing							
		urround Sense Module	207					
		Lakshit Kohli, Manglesh Saurabh, Ishaan Bhatia,						
		Sindhwani and Manjula Vijh Introduction	208					
	12.1		208					
		Existing System Proposed System	210					
		IoT Sensors and Architecture	210					
	12.4	12.4.1 Sensors and Theory	212					
		12.4.2 Architectures Available	213					
		12.4.2.1 3-Layer IoT Architecture	213					
		12.4.2.2 5-Layer IoT Architecture	213					
		12.4.2.3 Architecture & Supporting Modules	215					
		12.4.2.4 Integration Approach	215					
		12.4.2.5 System of Modules	216					
	12.5		217					
	12.6	Design	218					
		12.6.1 System Design	219					
		12.6.2 Auto-Leveling	219					
		12.6.3 Amphibious Landing Module	221					
		12.6.4 Processing Module	223					
		12.6.5 Surround Sense Module	223					
	12.7	Results	224					
	12.8	Conclusion	227					
	12.9	Future Scope	228					
		References	228					
3	Mind	Controlled Unmanned Aerial Vehicle (UAV)						
		g Brain-Computer Interface (BCI)	231					
		oth M.S., Naveen R. and Sivaraj G.						
	13.1	Introduction	232					
	10.1	13.1.1 Classification of UAVs	232					
		13.1.2 Drone Controlling	232					
	13.2	Mind-Controlled UAV With BCI Technology	233					
	13.3	Layout and Architecture of BCI Technology	234					
	13.4	Hardware Components	235					
		13.4.1 Neurosky Mindwave Headset	235					
		13.4.2 Microcontroller Board—Arduino	236					
		13.4.3 A Computer	237					
		13.4.4 Drone for Quadcopter	238					

				Contents	xiii	
	13.5	Softwa	re Compo	nents	239	
	10.0			ng P3 Software	239	
				IDE Software	240	
				ear Connector	240	
	13.6			oftware Integration	241	
		Conclu			243	
	1017	Referen			244	
14	Preci	sion Ag	riculture \	With Technologies for Smart		
		_		culture 5.0	247	
		•		Dilip Kumar Saini and Ajay Kumar		
	14.1			1	247	
	14.2	Drone	Technolog	gy as an Instrument for Increasing		
			Productivit	· · · · · · · · · · · · · · · · · · ·	248	
	14.3			cking of Rice Farm Areas		
				n and Communication Technology		
		(ICT) a	and Remot	te Sensing Technology	249	
		14.3.1 Methodology and Development of ICT				
	14.4					
		14.4.1	Latest Ag	gricultural Drone History	252	
		14.4.2	The Cha	llenges	254	
		14.4.3	SAP's Ne	ext Wave of Drone Technologies	254	
		14.4.4	SAP Cor	nnected Agriculture	256	
		14.4.5	Cases of	Real-World Use	<u>257</u>	
			14.4.5.1	Crop Surveying	257	
			14.4.5.2	Capture the Plantation	258	
			14.4.5.3	Image Processing	258	
			14.4.5.4	Working to Create GeoTiles		
				and an Image Pyramid	259	
	14.5	Drones		nsor Platforms	260	
		14.5.1		and Challenges	<u>260</u>	
		14.5.2		der and End Consumer Benefits	261	
		14.5.3	The Tech		262	
			14.5.3.1	Provisions of the Unmanned		
				Aerial Vehicles	262	
	14.6			hnology in Crop Insurance	263	
	14.7			ization of Drone Imaging Technologies		
		_		r Disaster Managing Risk	267	
		14.7.1		rn Working	267	
		14.7.2	Discover	ing Drone Mapping Technology	<u> 268</u>	

xiv Contents

		14.7.3	From Lo	wland to Uplands, Drone Mapping	
			Technolo	ogy	269
		14.7.4	Institutio	onalization of Drone Monitoring	
			Systems	and Farming Capability	269
	14.8	Usage of	of Internet	of Things in Agriculture and Use	
		of Unn	nanned Ae	rial Vehicles	270
		14.8.1	System a	nd Application Based on UAV-WSN	270
		14.8.2	Using a (Complex Comprehensive System	271
		14.8.3	Benefits .	Assessment of Conventional System	
			and the U	JAV-Based System	271
			14.8.3.1	Merit	272
			14.8.3.2	Saving Expenses	272
			14.8.3.3	Traditional Agriculture	273
			14.8.3.4	UAV-WSN System-Based Agriculture	273
	14.9	Conclu	sion		<u>273</u>
		Referer	nces		27 3
15	IoT-F	Rased U	AV Platfor	m Revolutionized in Smart Healthcare	277
				ilip Kumar Saini, Preeti Singh	
			ra Siddhai		
		Introdu		212	278
	15.2			Platform for Emergency Services	279
				net of Things: Technologies, Advantages	281
		15.3.1	Advantag		281
			15.3.1.1		281
			15.3.1.2		
				and Availability	282
			15.3.1.3	<u>-</u>	282
			15.3.1.4	Warnings and Recording	282
			15.3.1.5	Wellbeing Remote Assistance	283
			15.3.1.6	Research	283
		15.3.2	Complica	ations	283
			15.3.2.1	Privacy and Data Security	283
			15.3.2.2	Integration: Various Protocols	
				and Services	284
			15.3.2.3	Overload and Accuracy of Data	284
			15.3.2.4	Expenditure	284
	15.4			Applications: Surgical and Medical	
			ations of D		285
			Hearable		285
		15.4.2	Ingestible	e Sensors	285

Contents xv

		15.4.3	Moodables	285
		15.4.4	Technology of Computer Vision	286
		15.4.5	Charting for Healthcare	286
	15.5	Drones	That Will Revolutionize Healthcare	286
		15.5.1	Integrated Enhancement in Efficiency	286
		15.5.2	Offering Personalized Healthcare	<u>287</u>
		15.5.3	The Big Data Manipulation	287
		15.5.4	Safety and Privacy Optimization	287
		15.5.5	Enabling M2M Communication	288
	15.6	Health	care Revolutionizing Drones	288
		15.6.1	Google Drones	288
		15.6.2	Healthcare Integrated Rescue Operations (HiRO)	289
		15.6.3	EHang	289
		15.6.4	TU Delft	289
		15.6.5	Project Wing	289
		15.6.6	Flirtey	289
		15.6.7	Seattle's VillageReach	290
		15.6.8	ZipLine	290
	15.7	Conclu	sion	290
		Referer	nces	290
In	dex			295

Preface

Unmanned aerial vehicles (UAVs) have become one of the rapidly growing areas of technology, with widespread applications covering various domains. UAVs play a very important role in delivering Internet of Things (IoT) services in small and low-power devices such as sensors, cameras, GPS receivers, etc. These devices are energy-constrained and are unable to communicate over long distances. The UAVs work dynamically for IoT applications in which they collect data and transmit it to other devices that are out of the communication range. Furthermore, the benefits of the UAV include deployment at remote locations, the ability to carry flexible payloads, reprogrammability during tasks, and the ability to sense for anything from anywhere. Using IoT technologies, a UAV may be observed as a terminal device connected in the ubiquitous network, where many other UAVs are communicating, navigating, controlling, and surveilling in real time and beyond line-of-sight.

However, many significant research challenges should be addressed before bringing such UAV capabilities into practice. The aim of this book is to explore the theoretical as well as technical research outcomes of all aspects of UAVs. The UAV has drastically altered the perspectives of users, practitioners, and researchers in many fields of application such as disaster management, structural inspection, goods delivery, transportation, localization, mapping, pollution and radiation monitoring, search and rescue, farming, etc. The advancements introduced by UAVs are countless and have led the way for the full integration of UAVs as intelligent objects in the IoT.

This book helps to realize the full potential of the UAV for the IoT by addressing its numerous concepts, issues and challenges, and develops conceptual and technological solutions for handling them. It is comprised of 15 chapters authored by various renowned experts in the UAV and IoT fields. The book is organized as follows:

Chapter 1 presents a comprehensive survey of UAVs. The communication standards, workings, and various technologies of UAV are presented.

Also, platforms of different types of drones in various categories, their working, types, sizes, and other technology employed in making them are explored. Furthermore, the latest ongoing technology used in drones and their recent advancements are discussed.

Chapter 2 highlights the state-of-the-art, challenges encountered and the open research issues in designing UAV-aided wireless communication networks. A few of the challenges identified and presented include the best methods of 3D deployment of drones, allocation of resources, optimization of the flight time and trajectory of UAVs, handover management, channel modeling of highly dynamic UAV channels in various scenarios of UAV-assisted networks, interference management, effects of higher Doppler shifts in mmWave networks, on-board energy availability of UAV devices, etc.

Chapter 3 focuses on the techniques available for effective battery and energy management in UAV-based communication networks. The mechanisms for the optimal utilization of energy resources by UAVs to maximize their lifespan or deployment in a network are critically examined. This helps to significantly reduce the usage of network energy that results in a prolonged network lifetime. Furthermore, potentially promising areas for future research in energy management are also explored.

Chapter 4 emphasizes the most used communication techniques in UAVs. The state-of-the-art literature regarding UAV communication techniques and a summary of the same in the form of challenges and issues that arise when developing communication methods for UAVs are presented. A comprehensive performance comparison of UAV communication techniques is provided at the end of this chapter.

Chapter 5 discusses different challenges and threats posed by UAVs such as hijacking, privacy, cybersecurity, and physical safety. Also discussed are different solutions for avoiding these issues with current technologies.

Chapter 6 bridges the landscape between the IoT and the UAV by identifying the technical and nontechnical issues facing integration. Also presented are various applications, architecture, and technologies of the UAV-enabled IoT. This chapter answers the question regarding the proximity between IoT and UAV by exploiting the mobility of UAVs.

Chapter 7 introduces the practice of using UAVs for security and intelligence and also relates how drones are employed in different domains and for different purposes, including mischievous ones. Also, new experiments are presented related to security, safety, and privacy concerns when UAV drones are engaged in dangerous activities.

Chapter 8 explores blockchain-based solutions for various security issues in UAV-enabled IoT. Though the fusion of UAVs and IoT proves disruptive,

it is needed to address increased security issues. Identity management, authentication, UAV hijacking, secured and trustworthy data sharing in intra-UAV communications, and UAV signal jamming are explored in this chapter. Since blockchain is a decentralized technology, a distributed ledger offers solutions to some of these UAV issues presented here.

Chapter 9 introduces the efficient energy management systems in UAV-based IoT networks. The major constraint envisaged is the limited battery capacity of UAVs, proving them to be energy-constrained devices. The methods described here either harvest energy from RF signals or mmWaves, charge wirelessly from the charging station, or change the flight conditions for efficient energy utilization.

Chapter 10 contains an inclusive survey on the challenges and opportunities of IoE-enabled UAVs. There is a review of technologies enabling these opportunities, such as battery constraint, security issues, computing, and coverage constraints; and there is also an overview of UAVs. Finally, IoE-enabled UAV technology is presented that uses UAV deployment and mobility with IoE's intelligence, scalability, and diversity.

Chapter 11 provides a comprehensive survey of research for exploring applications of AI in UAV-enabled IoT systems with a specific focus on the research being conducted in the field of convergence of three disruptive technologies—namely, AI, UAVs, and the IoT—for improving the quality of life. The importance of AI in realizing an autonomous and intelligent flying IoT is emphasized.

Chapter 12 aims to follow a modular design approach to provide better functionality and a wide range of applications in all sorts of fields. It also incorporates the IoT in the UAV with all the sensor data of the surrounding environment with a UAV position that can be transmitted to a remote server and analyzed in real time.

Chapter 13 focuses on a mind-controlled UAV using brain-computer interface (BCI), which is a connection between the human brain and computers. The scope of this chapter is concentrated on the development boards which permit wireless communications.

Chapter 14 analyzes the new era farming system and the role of UAV technologies which help to improve the agricultural area to enable farmers to make cost-effective decisions while also preserving the ecosystem and changing how food is generated.

Chapter 15 explores the IoT-based UAV platform revolutionizing smart healthcare. The mobile phone industry and the IoT networks that are making robust data collection possible are rapidly being used in medical tools and software. This chapter discusses healthcare IoT technologies and their advantages for society.

xx Preface

In closing, we would like to thank our contributing authors for their valuable work, without which it would have been impossible to complete this book. We would also like to express our deepest appreciation to our reviewers for submitting their valuable comments in a timely manner. Last but not least, we thank GOD for giving us the strength and wisdom to carry out this work successfully even during tough circumstances due to the COVID-19 pandemic.

We hope that the quality research work published in the 15 chapters of this book will serve the needs of those in the academic, research, science and technology communities along with all of humanity.

Dr. Vandana Mohindru

Assistant Professor, Chandigarh Group of Colleges, Mohali, Punjab, India

Dr. Yashwant Singh

Associate Professor & Head, Department of Computer Science and IT, Central University of Jammu, J&K, India

Dr. Ravindara Bhatt

Assistant Professor (Senior Grade), Jaypee University of Information Technology, Solan, H.P., India

Dr. Anuj Kumar Gupta

Professor, Chandigarh Group of Colleges, Mohali, Punjab, India