

Course Code: 18B1WEC831

MAX. MARKS: 35

Course Name: Networked Embedded Control Systems

Course Credits: 03

MAX. 1.5 hrs

*Note: All questions are compulsory. Carrying of mobile phone during examinations will be treated as case of unfair means. Marks are indicated in square brackets against each question.*

Qu.1: (a) Derive the stability criterion of the closed-loop networked predictive control system having constant network delay. (CO-3) 2.5

(b) Describe networked predictive control system with giving details of control prediction generator and network delay compensator. (CO-3) 2.5

Qu.2: (a) Explain the following in intelligent space: (CO-1)  
(i) Edge detection for boundary detection  
(ii) Path tracking using quadratic curve fitting  
(iii) Impact of network delay on the performance of intelligent space 1.5+1.5+2=5

Qu.3: (a) Differentiate between the embedded system and cyber-physical systems (CPS). (CO-2) 2.5

(b) Define CPS and explain the following terms related with CPS:  
Cyber space, Physical space, Object domain and Real space (CO-2) 2.5

Qu.4: (a) With help of an example explain the dumb behavior of the sensor nodes (CO-2) 2.5

(b) With reference to WSN, explain the following detection scheme:  
(i) Single source single object detection scheme, (ii) Single source multiple object scheme (CO-2) 2.5

Qu.5: (a) Explain different type of actuators. Also explain, in what way actuator is related with the control systems. (CO-2) 2.5

(b) In case of IoT, explain: (i) network configuration, (ii) impact of mobility on addressing (CO-2) 2.5