## RAY TRACING USING JAVA

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Bachelor of Technology

## Computer Science and Engineering



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Under the Supervision of

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By

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## CERTIFICATE

This is to certify that the work titled "RAY TRACING USING JAVA" submitted by Mayank in partial fulfilment for the award of degree of B.Tech Computer Science and Engineering of Jaypee University of Information Technology, Waknaghat has been carried out under my supervision. This work has not been submitted partially or wholly to any other University or Institute for the award of this or any other degree or diploma.

Signature of Supervisor $\qquad$

Name of Supervisor $\qquad$

Designation

Date

## ACKNOWLEDGEMENT

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Signature of the student

Name of Student

Date

## SUMMARY

## Objective:

To develop a platform for ray tracing where we create a scene using a text file and then our java application will create a realistic image of the scene.

## Description:

Ray tracing is a technique to produce a realistic image virtually. This method converts a 3 dimensional image to 2 dimensional image to make it suitable for display on the computer screen. Ray tracing takes a lot of time in rendering the image, so it makes this technique suitable for applications where image can be generated before its actual use, for example television animation.
In this project I have developed a Java application for ray tracing in which we define a scene in a text file. This text file serves as an input to the application which then decodes this scene into the various individual objects and lights. Then we take a simple camera as our viewer that defines our image plane. We render the continuous image pixel by pixel by shooting a ray from each pixel to the image plane and then we check for the intersections. Finally we calculate the colour at that pixel and display it.

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## CHAPTER 1: INTRODUCTION

Ray tracing is a method to produce virtually realistic images and is based on global illumination rendering method. This method traces rays of light from the eye (the camera) to the image plane into the scene. Then these rays are checked against all objects present in the scene to determine if they intersect any of these. If the ray passes through the scene without any intersection, then that pixel is shaded with the background colour. Ray tracing's primary advantage is that it is relatively straightforward to compute shadows and reflections.

Ray tracing was first developed in 1960s by scientists of Mathematical Applications Group and is a point sampling algorithm where we sample a continuous image by producing one or more rays from each pixel. Hence, leading to one of the disadvantage - aliasing. Aliasing is corroborated in computer graphics by spiky edges.

This method is capable of rendering a very high degree of visual realism as it simply captures the natural method of image generation through the eye but at a great computational cost. This makes ray tracing suitable for applications where the image can be rendered beforehand, as in television animation, and poorly suited for dynamic applications like gaming where speed is of utmost importance.

A ray tracing program mathematically identifies the path that each ray follows in reverse direction i.e. from the eye back to its point of origin. Each path consist of one or more straight line components and nearly always involves refraction, reflection, or shadow effects from points within the scene. Rays are assigned a colour based on the pigments the objects in the scene that the ray passes through and each pixel on the display corresponds to a ray.

In the last decade or so the efficiency and the quality of computer graphics has increased significantly. However the need for a higher quality interactive graphics still persists. We need high quality interactive graphics effects such as reflections, shadows, refractions etc. The complex implementations of these effects can only be an approximation due to limitations of the rendering methods. Ray tracing has been a standard for non-interactive computer graphics. Recent research has shown that ray tracing is also possible for interactive applications too. In this thesis we discover more about ray tracing and its implementation in Java.

## CHAPTER 2: BRIEF SURVEY OF RAY TRACING

It necessary to be introduced with few terms before going into depth of ray tracing. "Ray tracing" actually covers a huge area in field of computer graphics, ranging from the basic concept of efficiently finding an intersection between a ray and set a primitives (plane and sphere in this project) to recursively tracing the images for realistic reflections. In computer graphics we typically want to know how our three dimensional image looks through a virtual camera. The process of computing image that such a virtual camera produces is called a rendering.

The current standard rendering method is a local illumination rendering method known as rasterization. This means that only the light from the light source is accounted for. Reflected rays and refracted rays do not contribute to the image.

To make the scene look more real we use ray tracing as it is a global illumination rendering method i.e. it takes into account the reflected and refracted rays too. This is requires for advanced effects such as reflection and shadows. Ray tracing works by tracing the path of light. We follow the path of rays of light

Of all the rays of light that is produced by light sources a lot of rays end up going away from our virtual camera. We only want to know which light rays enter our virtual camera and hence contribute to our image, so we follow the light backwards. This means that we start at our eye (the virtual camera) and trace, the ray determines the colour of the pixel we want to know about. When we encounter the point where the light is coming from we want to know the colour at that point. To calculate this colour we need to know what the incoming light at that point was. We recursively trace the rays from the light that falls on that point. Remember in a global illumination method the light can originate both from the light source or light reflected from other objects.

The main problem in ray tracing is to find the nearest intersection of the ray with an object. Though this is not covered in the implementation, I suggest using spatial index structure. Using sich structure we can check if a ray is in the vicinity of the object before we can check for an intersection.


Fig 1. The basic rendering method

This simple but flexible rendering method makes ray tracing a much more suitable environment for advanced effects than rasterization. With rasterization we need complex and non-intuitive operations for such effects and often these effects are not possible at all because of the limitations of a local illumination rendering method.

Although ray tracing is a far more suitable environment for advanced effects it is traditionally known as being slow compared to rasterization rendering. The big difference between ray tracing and rasterization is that they work the other way around: Rasterization takes a primitive and draws it on screen, which is a very fast operation. With ray tracing we look for each pixel which primitive is under it. Suppose for example we would want to render a simple cube: With rasterization we would simply draw 16 triangles. With ray tracing we would need more computations as we would need to trace rays for each pixel on screen. This is why ray tracing is traditionally known as being "slow" compared to rasterization rendering.

Ray tracing is not actually "slow", the rendering time being logarithmic with the size of the scene. It does however have a high initial cost. With a very complex scene with advanced effects, it would be more efficient to use ray tracing than rasterization. This is because the rasterization approach would always draw all triangles and overwrite triangles which are further away. This means a lot of redundant operations. Additionally if the advanced effects are at all possible they would need multiple rendering passes. With ray tracing we would simply have no redundant calculations and would not need multiple rendering passes. With highly complex and high quality graphics the cost of rasterization rendering, with its redundant calculations and ineffective advanced effects, is higher than the cost of ray tracing.


Fig 2. Illustration of rays, vectors and angles required in ray tracing

Ray-tracing finds its roots in the works of artists and mathematicians from centuries earlier. In Alberti's desire to understand the mathematics behind art and vision, he described sight and vision in a matter aligned perfectly with computer graphics, and especially ray-tracing. Alberti states: "Let us imagine the rays, like extended very fine threads gathered... going back together inside the eye where the sense of sight lines. They are like a trunk of rays
from which, like straight shoots, the rays are released and go out towards the surface in front of them"

According to Shirley and Morley (2003), ray-trace renderers are built upon a series of simple algorithms that are used, in turn, to generate digital images. In contrast to a rendering method like scan-line rendering, ray-trace rendering is becoming more-popular because of increased computing power and the renderers ability to cleanly solve problematic topics such as realistic material transparencies and object shadows.

Basic Ray-tracing Algorithm:
for(current pixel width : x )
for(current pixel height : y)
set tm = DOUBLEMAX;
for(every object)
if( ray intersects object)
calculate t;
if( $\mathrm{t}<\mathrm{tm}$ )
set $\mathrm{tm}=\mathrm{t}$;
if(tm=DOUBLEMAX)
draw background colour at pixel $\mathrm{x}, \mathrm{y}$
else
draw closest shape at pixel $\mathrm{x}, \mathrm{y}$

Draw all pixels to image

The algorithmic process of ray-tracing is simple to understand. There exist objects to create and methods for describing their connections. The base list of required objects to create are: camera, ray (a position and direction), two dimensional array of pixels (an empty image), lights, and shapes. All objects in the scene are connected via independently calculated rays. In order for the renderer to see objects and render them, those objects must be in the line of sight of the camera. The line of sight is calculated as a ray, whose originating position is the camera and whose direction is determined by the location of the empty image. Rays are cast into the scene and wherever these line of sight rays intersect with various shapes, the renderer calculates which object is hit first and what color that object is. The color is calculated by casting rays, from a point on the surface, into the scene. Each surface point is checked for facing direction toward or away from the light sources. Any surface section facing toward a light whose view of the light is unobstructed will receive a lighting contribution. This contribution is based also on the amount to which the surface section points toward the light.

## CHAPTER 3: MATHEMATICS INVOLVED

## Equation of the ray,

Our ray can be defined with an origin and a direction. These are 3D vectors i.e. have three components( $\mathrm{x}, \mathrm{y}, \mathrm{z}$ ). It will be useful later when our direction is normalised( whose length is 1 ). The path the ray takes can be represented as a parametric equation in $t$.
$P=O+D t$
( P is the position, O is the origin, and D is the direction).

As our direction vector is normalised, the distance traveled by the ray from the origin is $t$.

## Equation of Plane,

We can represent a normal to the plane using a vector(3D), and also a value to denote the distance to the origin (in the direction of the normal). Rather than the origin of the ray mentioned above, this is the distance to the origin at $(0,0,0)$. E.g. if we look in the positive direction down the Z -axis from 0 , we can amount to a wall 10 units away with a plane with a distance of 10 and a normal of $(0,0,-1)$.

The general equation for a plane is:

$$
a x+b y+c z+d=0
$$

Where d is the distance to the origin and $\mathrm{a}, \mathrm{b}$ and c are the x , y and z components of the normal. To make the later equation more incisive, we can rewrite the plane equation in vector form as:

$$
P \cdot N=-d
$$

( P is the position, N is the normal, and d is the distance from the origin. Also the dot is the dot product)

From the above equations we know that t is the distance the ray has travelled from the origin. Now we want to find out how far the ray has travelled if it intersects our plane. Solving the ray and plane equations simultaneously will lead us to the required result.

The plane equation:
$P \cdot N=-d$
Taking $P$ from the ray equation:
$(O+D t) \cdot N=-d$
The dot product is distributive, so we simplify:
$O \cdot N+(D t) \cdot N=-d$
Further:
$O \cdot N+t(D \cdot N)=-d$
Now arranging it,
$t(D \cdot N)=-d-O \cdot N$
A bit more...
$t=\frac{-d-C \cdot N}{D \cdot N}$

When the ray hits the plane, we can easily calculate the distance travelled by the ray using this formula. We can substitute this value into the ray equation to get the intersection point in 3D coordinates too.

The numerator and denominator are 0 in case the ray does not hit the plane.

After implementing what we have discussed so far, we will have a screen with half white (for the intersection hits) and half black (for the misses).

## Equation of Sphere,

Sphere's Parametric form :
$(\mathrm{P}-\mathrm{C}) .(\mathrm{P}-\mathrm{C})=\mathrm{R}^{2}$

P is the point on sphere, R is radius and C is the centre of sphere

Ray Equation in parametric form:
$\mathrm{P}=\mathrm{O}+\mathrm{Dt}$

Substituting ray equation in sphere equation:
$(\mathrm{O}+\mathrm{Dt}-\mathrm{C}) \cdot(\mathrm{O}+\mathrm{Dt}-\mathrm{C})-\mathrm{R}^{2}=0$

Expanding :
(D.D) $\mathrm{t}^{2}+2 \mathrm{D} \cdot(\mathrm{O}-\mathrm{C}) \mathrm{t}+(\mathrm{O}-\mathrm{C}) \cdot(\mathrm{O}-\mathrm{C})-\mathrm{R}^{2}=0$

This a quadratic equation in $t$ which gives us two roots which signifies two intersection point on sphere.

Rewriting the equation as:
$a t^{2}+b t+e=0$

Where:
$\mathrm{a}=\mathrm{D}^{2}$
$\mathrm{b}=2 \mathrm{D} .(\mathrm{O}-\mathrm{C})$
$\mathrm{e}=(\mathrm{O}-\mathrm{C}) \cdot(\mathrm{O}-\mathrm{C})-\mathrm{R}^{2}$

First we need to check whether ray is intersection with the sphere or not:

Determinant $=\sqrt{b^{2}-4 a c}$
$\sqrt{b^{2}-4 a c}<0 \Rightarrow$ No intersection
$\sqrt{b^{2}-4 a c}>0 \Rightarrow$ Two solutions (enter and exit)
$\sqrt{b^{2}-4 a c}=0 \Rightarrow$ One solution (ray grazes sphere)

## CHAPTER 4: COMPONENTS OF LIGHTING

Different types of light sources are used to give different effect:

## 1. Ambient part

This represents a fixed- intensity and also a fixed light source that affects each and every object in the scene equally. Ambient light is mainly used to give the scene a basic view of different objects present. It is very simple to implement and models how light is scattered or reflected many times producing a uniform effect.

Incoming Ambient Light Reflected Ambient Light


Fig 3. Ambient Light

The Mathematical term for ambient term,
ambient $=K_{\mathrm{a}} \times$ GA
Where:

- $\mathrm{K}_{\mathrm{a}}$ is the ambient reflectance of the material and
- GA is the Global Ambient i.e. the color of the incoming ambient light


## 2. Diffuse Part

The diffuse term is used for accounting the directed light reflected off a surface evenly in all the directions. Generally, diffuse surfaces are uneven on a minuscule scale, which reflect light in many directions. When incoming rays of light hit these aberrations, the light reflects in every directions.


Fig 4. Diffuse Light Scattering

The intensity of light reflected directly depends on the angle of incidence of the light striking the surface. Surfaces having a dull finish, are said to be diffuse. The contribution of diffuse component at any particular point on a surface does not change, regardless of where the viewpoint is.


Fig 5. The Diffuse Term

The Mathematical term for diffuse term,
diffuse $=K_{d} \times \operatorname{LC}$ x maximum(0, N.L)
Where:

- $K_{d}$ is the diffuse colour of the material,
- LC is the light colour i.e. the colour of the incoming diffuse light,
- N represents the normalized surface normal,
- L denotes the normalized vector toward the light source


Fig 6. Calculating Diffuse Lighting

The angle between vectors N and L is calculated by taking the dot product. The greater the dot product, the smaller the angle will be between the vectors, and the surface will receive more incident light. Negative dot product denotes surfaces that faces away from the light, so the maximum(0,N.L) in the equation makes sure that these surfaces show no diffuse lighting.

## 3. Specular Part

The specular term represents the light scattered from a surface mostly around the mirror direction. On very smooth and shiny surfaces, such as polished metals the specular term is most prominent. Figure 7 illustrates the concept of specular reflection


Fig 7. The Specular term

Unlike the diffuse and ambient lighting terms, the contribution of specular depends on the camera placement. If the camera is on a location that does not receive the reflected rays, the camera will not be able to see a specular highlight on the surface. The specular term also affected by the shininess component of the material and not only the specular colour component of the material. Less shiny surfaces have highlighted component spread on a larger area than compared to the shinier material where the highlight is tighter and to a point. We can see the difference between the different shininess components of material in the following figure.


Fig 8. Example of different shininess exponents
The Mathematical term for specular term,
specular $=K_{s} \times \operatorname{LC} \times$ facing $\times(\operatorname{maximum}(0, N \cdot H)){ }^{\text {shininess }}$
Where:

- $\mathrm{K}_{\mathrm{s}}$ is the specular colour of the material,
- LC is light colour i.e. the the incoming specular light's colour,
- N represents the normalized surface normal,
- V denotes the normalized vector toward the viewpoint,
- L represents the normalized vector toward the light source,
- H denotes the normalized vector that is halfway between V and L ,
- $P$ is the point that is to be shaded, and
- facing is 0 if $\mathrm{N} \cdot \mathrm{L}$ is less than 0 , and 1 otherwise.


Fig 9. Calculating the Specular term

The specular appearance of the material becomes evident when the angle between the view vector V and the half-angle vector H is small. As H and V move farther apart, the exponentiation of the dot product of N and H makes sure that the specular appearance falls off quickly.

Also, if the diffuse term is zero the specular term is forced to zero because $\mathrm{N} \cdot \mathrm{L}$ (from diffuse part) is negative. This makes sure that specular highlights is not visible on surfaces that faces away from the light.

Adding the terms(Ambient, Diffuse and Specular) together,


Fig 10. Lighting effect of the three components
A. Specular effect
B. Diffuse effect
C. Ambient effect

The individual effects are captured gain in Fig 9.


Fig 11. Putting the lighting terms together
Combining the ambient, diffuse, and specular terms gives the final lighting, as shown in Figure 10. Phong Reflection is the resulting Light effect.

## CHAPTER 5: IMPLEMENTATION IN JAVA

## Classes created:

1. SimpleCamera - SimpleCamera implements the viewer where the COP is on Z . A viewport is specified on the XY plane.
2. Vector - This class stores the 3D vector components and contains methods to manipulate the vectors.
3. Colour - Colour stores a RGB component and supports several methods to manipulate colour values
4. Sphere - Sphere represents a spherical object
5. DirectionalLight - DirectionalLight represents a light source that illuminates along parallel rays.
6. SimpleRay - SimpleRay implements the framework for the ray-tracing. It operates as an applet. It also implements a thread which periodically forces a screen repaint so that the user is kept aware of how far the ray-tracing has proceeded.
7. Light - This is superclass that each type of light must extend.
8. Material - Material describes the surface properties of an object using ambient, diffuse and specular components.
9. SceneReader - A class to read values from a file
10. SceneWriter - A simple output class to write values to a file.
11. Scene - Scene creates the scene and stores the different components in its respective classes
12. Point - Point stores and manipulates xyz triples representing 3 space points.
13. PointLight - PointLight represents a light sources that illuminates from a fixed origin
14. Object - Object superclass each type of object must extend and implement this class.
15. Plane - Plane represents an infinite plane object
16. Ray - Ray stores a ray origin point and direction vector.

## Class SimpleCamera

## Constructor

SimpleCamera()
Creates a camera with resolution of 200 by 200
SimpleCamera(int a, int b)
Creates a camera with width, a and height, $b$.

## Methods

| void | initBasic(int a, int b) |
| :---: | :---: |
| Ray | ray(int $x$, int $y)$ <br> Returns the ray number $x, y$ from the model of camera |
| void | setCOP (double cent) <br> Sets the centre of projection equal to cent on the Z axis |
| void | setResolution(int $x$, int $y$ ) <br> Set the resolution of the camera in terms of the number of rays to cast. |
| void | setVPWindow (double xmin, double xmax, double ymin, double ymax) Set the viewport window on the XY plane |

## Class Vector

## Variables

| double | $X$ | Holds the X component |
| :---: | :--- | :--- |
| double | $Y$ |  |
|  |  | Holds the $Y$ component |

## Constructor

```
Vector()
Creates a vector and initializes it to zero
```

```
Vector(double s, double b, double c)
```

Vector(double s, double b, double c)
Creates a vector with the given $\mathrm{a}, \mathrm{b}$ and c values

```
```

Vector(Point p)

```
Vector(Point p)
Point object is converted to a new vector
```

```
Vector(Vector v)
```

Vector(Vector v)
Creates a vector by imitating an existing vector

```
\begin{tabular}{|r|r|l|l|}
\hline Methods & & \begin{tabular}{c} 
void \\
This vector is added to the given vector
\end{tabular} \\
\hline Vector & \begin{tabular}{l} 
add (Vector a, Vector b) \\
The two vectors are added and written it to a given destination \\
vector.
\end{tabular} \\
\hline void & \begin{tabular}{l} 
add (Vector vd, Vector v1, Vector v2) \\
Two vectors are added and written it to a given destination \\
vector.
\end{tabular} \\
\hline void & \begin{tabular}{c} 
copy (Vector a) \\
An existing vector is copied to this vector
\end{tabular} \\
\hline void & \begin{tabular}{c} 
cross (Vector a) \\
Cross product is calculated with this vector
\end{tabular} \\
\hline Vector & \begin{tabular}{l} 
cross (Vector a, Vector b) \\
A new vector is returned with the cross product of the two \\
given vectors.
\end{tabular} \\
\hline void & \begin{tabular}{l} 
cross (Vector vd, Vector v1, Vector v2) \\
Cross product of the two given vectors is written to the given \\
desination vector.
\end{tabular} \\
\hline double & \begin{tabular}{l} 
dot (Point p) \\
Dot product of point and the vector is calculated.
\end{tabular} \\
\hline double & \begin{tabular}{l} 
dot (Vector v) \\
Dot product of the two vectors
\end{tabular} \\
\hline double & \begin{tabular}{l} 
dot (Vector v1, Vector v2) \\
Returns the dot product of the two given vectors.
\end{tabular} \\
\hline
\end{tabular}
\begin{tabular}{|c|c|}
\hline void & \begin{tabular}{l}
negate() \\
Vector is negated
\end{tabular} \\
\hline Vector & \begin{tabular}{l}
negate (Vector a) \\
Creates a new vector after negating a given vector.
\end{tabular} \\
\hline double & \begin{tabular}{l}
norm () \\
Length of this vector is calculated
\end{tabular} \\
\hline void & \begin{tabular}{l}
normalise() \\
Vector is normalized
\end{tabular} \\
\hline Vector & \begin{tabular}{l}
normalised() \\
Creates a new vector as the normalization of this vector
\end{tabular} \\
\hline void & \begin{tabular}{l}
print (SceneWriter ofs) \\
Prints a human readable form of the vector
\end{tabular} \\
\hline void & \begin{tabular}{l}
read (SceneReader ifs) \\
Read the vector from the given source
\end{tabular} \\
\hline void & \begin{tabular}{l}
scale(double sc) \\
The vector is scaled by the given factor sc
\end{tabular} \\
\hline Vector & \begin{tabular}{l}
scale (Vector a, double sc) \\
Scale method creates a vector by scaling a existing vector.
\end{tabular} \\
\hline void & \begin{tabular}{l}
scale (Vector \(d\), Vector \(a\), double sc) \\
Scale method that writes a vector after scaling the given vector.
\end{tabular} \\
\hline Void & \begin{tabular}{l}
Set (double a, double b, double c) \\
Vector is set to the given \(\mathrm{a}, \mathrm{b}\) and c values
\end{tabular} \\
\hline double & \begin{tabular}{l}
squarednorm() \\
Squared length of this vector is calculated
\end{tabular} \\
\hline Vector & \begin{tabular}{l}
subtract(Point a, Point b) \\
Creates a vector and initializes as the difference between points a and b .
\end{tabular} \\
\hline void & \begin{tabular}{l}
subtract (Vector a) \\
The given vector is subtracted from this vector
\end{tabular} \\
\hline void & \begin{tabular}{l}
subtract (Vector d, Point a, Point b) \\
The difference between two points is calculated and written it the destination vector.
\end{tabular} \\
\hline void & \begin{tabular}{l}
subtract (Vector \(d\), Vector \(a\), Vector \(b\) ) \\
The difference between two vectors is calculated and written to the given destination vector.
\end{tabular} \\
\hline void & \begin{tabular}{l}
write (SceneWriter ofs) \\
Write the vector to the given destination
\end{tabular} \\
\hline
\end{tabular}

\section*{Class Colour}

\section*{Field Summary}
\begin{tabular}{|c|ll|}
\hline double & B & Holds the blue component of the colour \\
\hline double & G & \begin{tabular}{l} 
Holds the green component of the colour
\end{tabular} \\
\hline double & R & Holds the red component of the colour \\
\hline
\end{tabular}

\section*{Constructor Summary}

Colour()
Create a new colour and set it to the default colour (black)
```

Colour(Colour c)

```

Create a new colour by copying an existing colour
Colour(double r, double \(g\), double b)
Create a new colour with the given red green and blue values

\section*{Method Summary}
\begin{tabular}{|c|c|}
\hline void & \begin{tabular}{l}
add (Colour c) \\
Add the given colour to this colour
\end{tabular} \\
\hline Colour & \begin{tabular}{l}
add (Colour c1, Colour c2) \\
Implementation of colour add function that creates a new colour object from the result.
\end{tabular} \\
\hline void & \begin{tabular}{l}
add (Colour cd, Colour c1, Colour c2) \\
Implementation of colour add function that write the result of the addition to a given colour object.
\end{tabular} \\
\hline void & \begin{tabular}{l}
clamp() \\
Clamp each component of the colour to lie within the range 0.0 to 1.0
\end{tabular} \\
\hline void & \begin{tabular}{l}
copy (Colour c) \\
Copying an existing colour to this colour
\end{tabular} \\
\hline boolean & \begin{tabular}{l}
isBlack() \\
Test if the colour is black
\end{tabular} \\
\hline void & \begin{tabular}{l}
mult (Colour c) \\
Multiply the given colour to this colour
\end{tabular} \\
\hline
\end{tabular}
\begin{tabular}{|c|c|}
\hline Colour & \begin{tabular}{l}
mult (Colour c1, Colour c2) \\
Implementation of colour mult function that creates a new colour object from the result.
\end{tabular} \\
\hline void & \begin{tabular}{l}
mult (Colour cd, Colour c1, Colour c2) \\
Implementation of colour mult function that write the result of the multiplication to a given colour object.
\end{tabular} \\
\hline void & \begin{tabular}{l}
print (SceneWriter os) \\
Print a human readable version of the colour definition to the given destination
\end{tabular} \\
\hline void & \begin{tabular}{l}
read (SceneReader is) \\
Read the colour from the given source
\end{tabular} \\
\hline void & \begin{tabular}{l}
reset() \\
Reset the colour to the default colour (black)
\end{tabular} \\
\hline void & \begin{tabular}{l}
scale(Colour cd, Colour c1, double s) \\
Scale function that writes the colour scaled by the given factor to a given destination
\end{tabular} \\
\hline Colour & \begin{tabular}{l}
scale (Colour c1, double s) \\
Scale function that returns a new colour scaled by the given factor
\end{tabular} \\
\hline void & \begin{tabular}{l}
scale(double s) \\
Scale this colour by the given factor
\end{tabular} \\
\hline void & \begin{tabular}{l}
write (SceneWriter os) \\
Write the colour to the given destination
\end{tabular} \\
\hline
\end{tabular}

\section*{Class Sphere}

\section*{Field Summary}
\begin{tabular}{|c|c|}
\hline Point & \begin{tabular}{c} 
Centre \\
Holds the point that defines the sphere centre
\end{tabular} \\
\hline double & \begin{tabular}{c} 
Radius \\
Holds the radius of the sphere
\end{tabular} \\
\hline
\end{tabular}

\section*{Constructor Summary}
```

Sphere()
Create a default sphere

```
```

Sphere(Material n, Point p, double r)

```
```

Sphere(Material n, Point p, double r)

```

Create a sphere with the given material, centre and radius Note values are referenced not copied in the new object

Method Summary
\begin{tabular}{|c|l|}
\hline double & \begin{tabular}{c} 
intersect (Ray ray) \\
Find the intersection of the plane and a given ray.
\end{tabular} \\
\hline Vector & \begin{tabular}{c} 
normal (Point p) \\
Find the normal of an object at the given point on its surface.
\end{tabular} \\
\hline void & \begin{tabular}{c} 
print (SceneWriter os) \\
Print a human readable version of the sphere definition to the given \\
destination
\end{tabular} \\
\hline void & \begin{tabular}{c} 
read (SceneReader is) \\
Read the sphere from the given source
\end{tabular} \\
\hline void & \begin{tabular}{c} 
write (SceneWriter os) \\
Write the sphere to the given destination
\end{tabular} \\
\hline
\end{tabular}

\section*{Class DirectionalLight}

\section*{Field Summary}


\section*{Constructor Summary}

DirectionalLight()
Create a default light.
DirectionalLight (Vector v)
Create a new directional light that shines along given direction vector.

\section*{Method Summary}
\begin{tabular}{|c|c|}
\hline void & \begin{tabular}{c} 
print (SceneWriter os) \\
Print a human readable version of the light definition to the given destination
\end{tabular} \\
\hline void & \begin{tabular}{c} 
read (SceneReader is) \\
Read the light from the given source.
\end{tabular} \\
\hline void & \begin{tabular}{c} 
write (SceneWriter os) \\
Write the light to the given destination
\end{tabular} \\
\hline
\end{tabular}

\section*{Class SimpleRay}

\section*{Method Summary}
\begin{tabular}{|r|r|}
\hline void & \begin{tabular}{c} 
init () \\
Method for applet initialize The scene to read is taken from the \\
"scene" property in the applet tag on the web page.
\end{tabular} \\
\hline void & \begin{tabular}{c} 
paint (java.awt. Graphics g) \\
Paints the screen
\end{tabular} \\
\hline void & \begin{tabular}{c} 
run() \\
Run method is called by the "kicker" thread.
\end{tabular} \\
\hline void & \begin{tabular}{c} 
start () \\
Method called to start an applet after initialization.
\end{tabular} \\
\hline void & \begin{tabular}{c} 
stop () \\
Method called to stop an applet after initialization.
\end{tabular} \\
\hline void & \begin{tabular}{c} 
update (java.awt. Graphics g)
\end{tabular} \\
\hline
\end{tabular}

\section*{Class Light}

\section*{Field Summary}
```

Colour
Intensity
Holds the colour of this light

```

\section*{Constructor Summary}

Light()

\section*{Method Summary}
abstract void \begin{tabular}{l} 
print(SceneWriter os) \\
Print a human readable version of the light definition to the given \\
destination
\end{tabular}
\begin{tabular}{|lc|r} 
abstract void & \begin{tabular}{r} 
read(SceneReader is) \\
Read the light from the given source
\end{tabular} \\
\hline abstract void & \begin{tabular}{r} 
write (SceneWriter os) \\
Write the light to the given destination
\end{tabular} \\
\hline
\end{tabular}

\section*{Class Material}

Field Summary
\begin{tabular}{|c|c|}
\hline Colour & \begin{tabular}{c} 
Ambient \\
Holds the ambient component of this surface
\end{tabular} \\
\hline Colour & \begin{tabular}{c} 
Diffuse \\
Holds the ambient component of this surface
\end{tabular} \\
\hline double & \begin{tabular}{c} 
Shininess \\
Holds the shininess factor this surface
\end{tabular} \\
\hline Colour & \begin{tabular}{c} 
Specular \\
Holds the specular component of this surface
\end{tabular} \\
\hline
\end{tabular}

\section*{Constructor Summary}
```

Material()
Create a default material

```
```

Material(Material m)

```

Create a new material by copying an existing material.
\begin{tabular}{|c|l|}
\hline Method Summary \\
\hline void & \begin{tabular}{l} 
print (Scenewriter os) \\
Print a human readable version of the material definition to the given \\
destination
\end{tabular} \\
\hline void & \begin{tabular}{c} 
read (SceneReader is) \\
Read the material from the given source
\end{tabular} \\
\hline void & \begin{tabular}{l} 
write (Scenewriter os) \\
Write the material to the given destination
\end{tabular} \\
\hline
\end{tabular}

\section*{Class SceneReader}
\begin{tabular}{|r|r|l|}
\hline Method Summary \\
\hline void & \begin{tabular}{r} 
close () \\
Close the file when finished
\end{tabular} \\
\hline boolean & \begin{tabular}{r} 
eof () \\
Return true if the end of file has been reached.
\end{tabular} \\
\hline char & \begin{tabular}{c} 
readChar () \\
Read a char value from file.
\end{tabular} \\
\hline double & \begin{tabular}{r} 
readDouble () \\
Read a double value from file.
\end{tabular} \\
\hline float & \begin{tabular}{r} 
readFloat () \\
Read a float value from file.
\end{tabular} \\
\hline int & \begin{tabular}{r} 
readInt () \\
Read an int value from file.
\end{tabular} \\
\hline long & \begin{tabular}{r} 
readLong () \\
Read a long value from file.
\end{tabular} \\
\hline
\end{tabular}

\section*{Class SceneWriter}

\section*{Constructor Summary}

SceneWriter(java.io.File f)
Construct SceneWriter object given a file.
SceneWriter (java.io.OutputStream os)
Create a SceneWriter from a stream

\section*{Method Summary}
\begin{tabular}{|c|c|}
\hline void & \begin{tabular}{c} 
flush() \\
Flush the writer
\end{tabular} \\
\hline void & \begin{tabular}{c} 
writeChar (char c) \\
Write a char value to a file.
\end{tabular} \\
\hline
\end{tabular}
\begin{tabular}{|c|c|}
\hline void & \begin{tabular}{c} 
writeDouble (double d) \\
Write a double value.
\end{tabular} \\
\hline void & \begin{tabular}{c} 
writeFloat (float f) \\
Write a float value.
\end{tabular} \\
\hline void & \begin{tabular}{c} 
writeInt (int i) \\
Write an int value to a file.
\end{tabular} \\
\hline void & \begin{tabular}{c} 
writeLong (long l) \\
Write a long value.
\end{tabular} \\
\hline void & \begin{tabular}{c} 
writeNewline () \\
Write a newline to a file.
\end{tabular} \\
\hline void & \begin{tabular}{c} 
writeString (java.lang. String s) \\
Write a String value to a file.
\end{tabular} \\
\hline
\end{tabular}

\section*{Class Scene}

\section*{Field Summary}

\author{
Colour Ambient
}

\section*{Method Summary}
\begin{tabular}{|r|l|}
\hline int & getNumberLights() \\
\hline int & getNumberObjects() \\
\hline boolean & intersect(Ray ray, Colour colour, int depth) \\
\hline void & print(SceneWriter os) \\
\hline void & read(SceneReader is) \\
\hline void & setLight(int i, Light o) \\
\hline void & setNumberLights(int n) \\
\hline
\end{tabular}
\begin{tabular}{|r|l|}
\hline & \\
\hline void & setNumberObjects(int \(n\) ) \\
\hline void & setObject(int i, Object o) \\
\hline void & write(SceneWriter os) \\
\hline
\end{tabular}

\section*{Class Point}

\section*{Field Summary}
\begin{tabular}{|c|lc|}
\hline double & X & Holds the X component \\
\hline double & Y & Holds the Y component \\
\hline double & Z & Holds the Z component \\
\hline
\end{tabular}

\section*{Constructor Summary}

Point()
Create a new point and set it to zero
```

Point(double x, double y, double z)

```

Create a new point with the given \(x, y\) and \(z\) values
```

Point(Point p)

```

Create a new point by copying an existing point

\section*{Method Summary}
\begin{tabular}{|c|c|}
\hline void & \begin{tabular}{l} 
add (Point pd, Point p, Vector v) \\
Function that write addition of a point by adding a vector to a given \\
destiation point
\end{tabular} \\
\hline Point & \begin{tabular}{c} 
add (Point p, Vector v) \\
Function create a new point by adding a vector to a point.
\end{tabular} \\
\hline void & \begin{tabular}{c} 
add (Vector v) \\
Add the given offset vector to this point
\end{tabular} \\
\hline
\end{tabular}
\begin{tabular}{|r|r|}
\hline void & \begin{tabular}{c} 
copy (Point p) \\
Copy an existing point to this point
\end{tabular} \\
\hline boolean & \begin{tabular}{c} 
equals (Point p) \\
Test if two points are equal
\end{tabular} \\
\hline void & \begin{tabular}{c} 
print (SceneWriter os) \\
Print a human readable version of the point definition to the given \\
destination
\end{tabular} \\
\hline void & \begin{tabular}{c} 
read (SceneReader is) \\
Read the point from the given source
\end{tabular} \\
\hline void & \begin{tabular}{c} 
set (double x, double y, double z) \\
Set this point to the given x,y and z values
\end{tabular} \\
\hline void & \begin{tabular}{c} 
write (SceneWriter os) \\
Write the point to the given destination
\end{tabular} \\
\hline
\end{tabular}

\section*{Class PointLight}

\section*{Field Summary}
```

Point Origin

```

Stores the origin of the point light.

\section*{Constructor Summary}

PointLight()
Create a default light.
PointLight (Point p)
Create a new point light that at the given point.

\section*{Method Summary}
\begin{tabular}{|c|c|}
\hline void & \begin{tabular}{c} 
print (SceneWriter os) \\
Print a human readable version of the light definition to the given destination
\end{tabular} \\
\hline void & \begin{tabular}{c} 
read (SceneReader is) \\
Read the light from the given source
\end{tabular} \\
\hline void & \begin{tabular}{c} 
write (SceneWriter os) \\
Write the light to the given destination
\end{tabular} \\
\hline
\end{tabular}

\section*{Class Object}

Field Summary
\begin{tabular}{|l|r|}
\hline Material & \begin{tabular}{r} 
SurfaceMaterial \\
Holds the material of this object
\end{tabular} \\
\hline
\end{tabular}

\section*{Method Summary}
\begin{tabular}{|cc|c|}
\hline abstract double & \begin{tabular}{c} 
intersect (Ray ray) \\
Find the intersection of an object and a given ray.
\end{tabular} \\
\hline abstract Vector & \begin{tabular}{c} 
normal (Point pt) \\
Find the normal of an object at the given point on its surface.
\end{tabular} \\
\hline abstract void & \begin{tabular}{c} 
print (SceneWriter os) \\
Print a human readable version of the object definition to the \\
given destination
\end{tabular} \\
\hline abstract void & \begin{tabular}{r} 
read (SceneReader is) \\
Read the object from the given source
\end{tabular} \\
\hline abstract void & \begin{tabular}{r} 
write (SceneWriter os) \\
Write the object to the given destination
\end{tabular} \\
\hline
\end{tabular}

\section*{Class Plane}

\section*{Field Summary}
\begin{tabular}{|c|c|}
\hline double & \begin{tabular}{c} 
Constant \\
Holds the constant of the plane equation
\end{tabular} \\
\hline Vector & \begin{tabular}{c} 
Normal \\
Holds the normal that defines this plane
\end{tabular} \\
\hline
\end{tabular}

\section*{Constructor Summary}
```

Plane()

```

Create a default plane
```

Plane(Material n, Vector v, double c)

```

Create a plane with the given material and plane equation Note values are referenced not copied in the new object

\section*{Class Ray}

Field Summary
\begin{tabular}{|c|c|}
\hline Vector & \begin{tabular}{c} 
Direction \\
Holds the ray direction
\end{tabular} \\
\hline Point & \begin{tabular}{c} 
Origin \\
Holds the ray origin
\end{tabular} \\
\hline
\end{tabular}

\section*{Method Summary}

\author{
Point getPointAt (double \(t\) ) \\ Get a point along a ray.
}

CHAPTER 6: RESULT

\section*{The scene file:}
```


# number of objects

9

```
\#right wall
\(1-1.0 \quad 0.0 \quad 0.0 \quad-2.0 \quad 0.90 .90 .30 .80 .80 .1 \quad 0.00 .00 .0 \quad 2.0\)
\#bottom wall
\(\begin{array}{llllllllllllllllllllll}1 & 0.0 & 1.0 & 0.0 & -2.0 & 0.2 & 0.2 & 0.2 & 0.1 & 0.1 & 0.1 & 0.7 & 0.7 & 0.7 & 2.0\end{array}\)
\#top wall
\(1 \begin{array}{llllllllllllllllllllll}1 & 0.0 & -1.0 & 0.0 & -2.0 & 0.3 & 0.9 & 0.3 & 0.1 & 0.8 & 0.1 & 0.0 & 0.0 & 0.0 & 2.0\end{array}\)
\#left wall
\(\begin{array}{lllllllllllllllllll}1 & 1.0 & 0.0 & 0.0 & -2.0 & 0.3 & 0.3 & 0.9 & 0.1 & 0.1 & 0.8 & 0.0 & 0.0 & 0.0 & 2.0\end{array}\)
\#back wall
\(\begin{array}{lllllllllllllll}1 & 0.0 & 0.0 & 1.0 & -2.0 & 0.9 & 0.3 & 0.3 & 0.8 & 0.1 & 0.1 & 0.0 & 0.0 & 0.0 & 2.0\end{array}\)
\#sphere 1
\(\begin{array}{llllllllllllllllllllllll}0 & 1.2 & 0.4 & -0.4 & 0.5 & 0.2 & 0.2 & 0.2 & 0.6 & 0.4 & 0.2 & 0.1 & 0.3 & 0.3 & 5.0\end{array}\)
\#sphere 2

\#sphere 3
\(0-1.0 \quad 0.0-1.0 \quad 1.0 \quad 0.0 \quad 0.0 \quad 0.0 \quad 0.0 \quad 0.0 \quad 0.0 \quad 0.80 .80 .8 \quad 5.0\)
\#sphere 4
\(\begin{array}{lllllllllllllllllllllllllllll}0 & 1.0 & -0.6 & 0.0 & 0.5 & 0.2 & 0.2 & 0.2 & 0.6 & 0.4 & 0.2 & 0.1 & 0.3 & 0.3 & 5.0\end{array}\)
\#ambient colour
0.30 .30 .3
\#number lights
2
\# light 1 - point light
\(00.30 .50 .5-1.91 .90 .0\)
\# light 2 - directional light
\(10.80 .30 .31 .90 .0 \quad 0.0\)

\section*{Interpretation:}

Scene has 9 objects
Scene has 2 lights

Number of objects 9
Plane with normal: \([-1.0,0.0,0.0]\) and constant: -2.0

Material: ambient ( \(0.9,0.9,0.3\) ) diffuse ( \(0.8,0.8,0.1\) ) specular ( \(0.0,0.0,0.0\) ) shininess 2.0

Plane with normal: [0.0,1.0,0.0] and constant: -2.0
Material: ambient ( \(0.2,0.2,0.2\) ) diffuse \((0.1,0.1,0.1)\) specular \((0.7,0.7,0.7)\) shininess 2.0

Plane with normal: [0.0,-1.0,0.0] and constant: -2.0
Material: ambient ( \(0.3,0.9,0.3\) ) diffuse \((0.1,0.8,0.1)\) specular \((0.0,0.0,0.0)\) shininess 2.0

Plane with normal: [1.0,0.0,0.0] and constant: -2.0
Material: ambient \((0.3,0.3,0.9)\) diffuse \((0.1,0.1,0.8)\) specular \((0.0,0.0,0.0)\) shininess 2.0

Plane with normal: [0.0,0.0,1.0] and constant: -2.0
Material: ambient ( \(0.9,0.3,0.3\) ) diffuse ( \(0.8,0.1,0.1\) ) specular ( \(0.0,0.0,0.0\) ) shininess 2.0

Sphere with centre: [1.2,0.4,-0.4] and radius: 0.5
Material: ambient \((0.2,0.2,0.2)\) diffuse \((0.6,0.4,0.2)\) specular \((0.1,0.3,0.3)\) shininess 5.0

Sphere with centre: [0.0,-0.6,0.0] and radius: 0.4

Material: ambient (1.0,1.0,1.0) diffuse (1.0,1.0,1.0) specular (0.0,0.0,0.0) shininess 2.0

Sphere with centre: [-1.0,0.0,-1.0] and radius: 1.0
Material: ambient \((0.0,0.0,0.0)\) diffuse \((0.0,0.0,0.0)\) specular \((0.8,0.8,0.8)\) shininess 5.0

Sphere with centre: [1.0,-0.6,0.0] and radius: 0.5
Material: ambient \((0.2,0.2,0.2)\) diffuse \((0.6,0.4,0.2)\) specular \((0.1,0.3,0.3)\) shininess 5.0

Ambient light is 0.30 .30 .3
Number of lights 2

Point light with colour: \((0.3,0.5,0.5)\) and origin: [-1.9,1.9,0.0]
Directional light with colour: \((0.8,0.3,0.3)\) and direction: [1.9,0.0,0.0]

\section*{Rendering of the scene:}
1. The Original scene :


Fig 12. The Original Scene before applying lighting and shadows
2. After applying lighting


Fig 13. Scene after applying lighting
3. After applying shadows and reflections


Fig 14. The final rendered image

\section*{CHAPTER 7: CONCLUSION}

In this project we see how we can generate a realistic image through ray tracing by using backward tracing where we shoot a ray from the camera to the scene and see where it hits and then calculate the colour at that pixel. Ray tracing can be used in non-interactive applications where we can generate images beforehand and then display it when needed, as it takes a lot of time in rendering it is not suitable for interactive applications however through parallelism we can still think of such implementations. In the program developed in this project we can define any scene consisting of plane and spheres through a data file containing its coordinates and RGB components of diffuse, ambient and specular lighting components. The number of recursive reflections depend on the exponential shininess component. Through suitable mathematical equations we can further extend this project to other primitives such as triangles, cylinders etc.

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