

## Mid Semester Examination

Summer Semester June 2018

Course Code: 10B11EC512  
Time: 2 Hours

Course Name: Digital Signal Processing  
Max. Marks: 50

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- Q1. Define LTI system with a suitable example. Also explain the properties of LTI system. [10]
- Q2. Check whether the following systems are linear and time invariant [10]
- (a)  $y(n) = nx^2(n)$       (b)  $y(n) = mx(n) + c$
- Q3. Find out the convolution of the following signals: [10]
- (a)  $x(n) = \left(\frac{1}{2}\right)^n u(n)$ ,  $h(n) = u(n)$   
(b)  $x(n) = \{1\ 2\ 5\ 4\ 3\}$ ,  $h(n) = \{1\ 2\ 5\ 4\ 3\}$
- Q4. Check the causality and stability of systems defined by the following impulse responses: [10]
- (a)  $h(n) = \left(-\frac{1}{2}\right)^n u(n) + (1.01)^n u(n-1)$   
(b)  $h(n) = 5^n u(3-n)$
- Q5. Determine the zero state response of the system described by the following difference equation [10]
- $y(n) - 0.6y(n-1) - 0.16y(n-2) = x(n)$  when the input is  $x(n) = 4^{-n}u(n)$ .